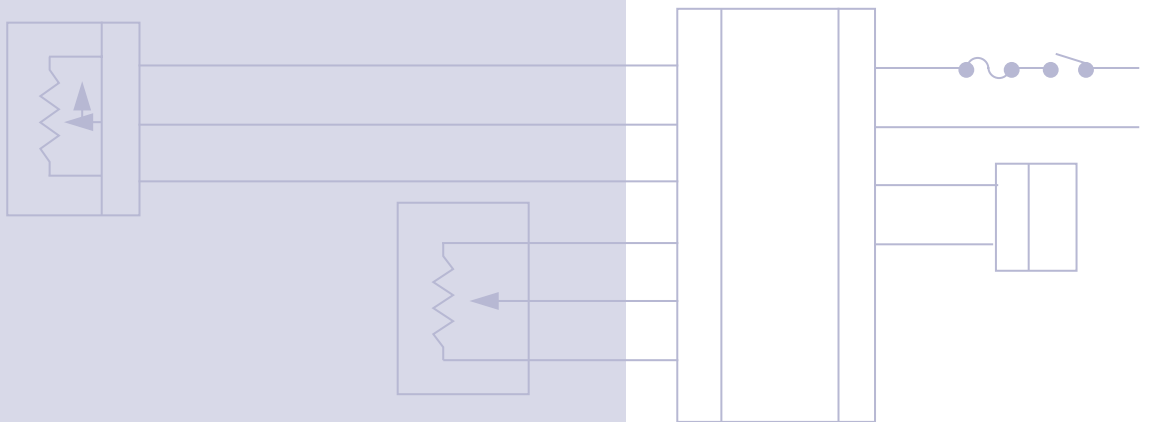




ACX104B  
Potentiometer  
Rotary Position  
Sensor

Technical  
Information



## Revision History

### *Table of Revisions*

Date	Page	Changed	Rev
29 July, 2010		Initial release	AA

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# ACX104B Potentiometer Rotary Position Sensor

## Technical Information

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#### Description

The ACX104B Potentiometer Rotary Position/Steering Sensor is a versatile control module applicable in a wide range of machine uses. In rotary position use, the sensor measures the relative height of the machine in relation to an external reference such as a stringline. In steering use, the sensor measures the machine's relative distance from a reference such as a curb. In both cases, the electrical signal is fed into a controller such as the ACE100A and, in steering usage, is compared to an ACX104C track or wheel feedback system. The ACX104B provides the necessary sensing control for rotary position or steering machinery such as asphalt or slipform pavers.

Signals come from an internal potentiometer that rotates directly with the outer hub. A follower attached to the hub provides a means of tracing a stringline or other reference surface. Follower movement rotates the shaft of the potentiometer, giving proportional signal to the controller. Typically the controller will be used to drive a V7059A Servovalve or KVF Flow Control Servovalve to reposition the machine as deviations occur.

#### Features

- Adjustable spring bias on the hub varies the follower tension on the stringline or reference surface
- Rugged housing
- Resists corrosion, moisture and other damaging environmental effects
- Compact unit can be mounted on almost any surface
- Connections between controller and sensor are made easily through MS connectors
- Easy to remove for service or replacement
- Two position (Run/Standby) switch available

#### Ordering Information

##### Specifications

<b>ACX104B1002</b>	1 kilohm, 90° potentiometer, without switch.
<b>ACX104B1028</b>	Auto/Manual ON/OFF switch, no mounting tabs
<b>ACE100A</b>	Controller, order if needed.
<b>KVF</b>	Servovalve
<b>KW01009</b>	Cable assembly, can be used to provide connections. The two-foot coiled cable extends to ten feet.
<b>K04185</b>	Mating connector
<b>Follower</b>	Order as necessary, see Installation, Wiring section.



# ACX104B Potentiometer Rotary Position Sensor

## Technical Information

### Technical Data

#### Electrical

##### Data

<b>Input voltage</b>	24 Volts maximum
<b>Output voltage</b>	30% to 70% of input
<b>Resistance</b>	1000 ohms, +20%

##### Travel

Physical stops limit travel to approximately 20 degrees (18 degrees minimum). The potentiometer wiper is electrically centered when the indicator line on the hub is parallel to the mark on the case.

##### Phasing

Resistance between Pins A and B of the MS connector will increase when the hub is rotated clockwise.

#### Environmental

##### Vibration

Withstands a vibration test designed for mobile equipment devices that includes two parts:

1. Cycling from 5 to 2000 Hz over a range of +1.0 g's to +8.0 g's for a period of one hour (if there are four resonant points), for two hours (if there are two or three resonant points) and for three hours (if there is one or no resonant point). The cycling test is performed on each of the three major axes.
2. Resonance dwell for one million cycles over a range of +1.0 g's to +8.0 g's for each of the four most severe resonant points on each of the three major axes.

##### Shock

Withstands a shock test for mobile equipment devices that consists of three shocks of 50 g's and 11 milliseconds duration in both directions of the three major axes for a total of 18 shocks.

##### Temperature

<b>Operating Temperature</b>	-18° to 77° C (0° to 170° F)
<b>Storage Temperature</b>	-40° to 77° C (-40° to + 170° F)

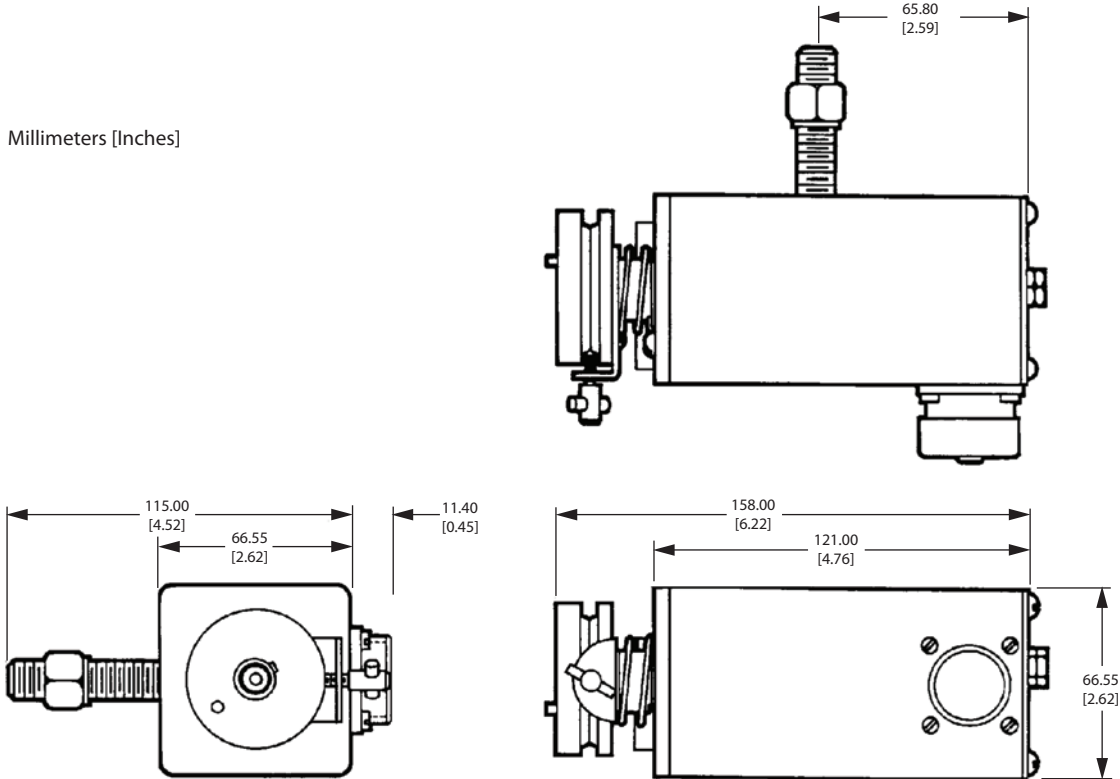
#### Weight

<b>Weight</b>	1.2 kg (2 pounds, 9 ounces)
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**Dimensions**

*ACX104B Without Flanges Mounting Dimensions*

Millimeters [Inches]



P200 012

**Location**

The ACX104B may be mounted on either the left or right side of the machine with the hub and follower outward. A mounting stud extends from the back of the case. It must be inserted through a vertical plate that is attached to an appropriate height-adjusting jack. The mounting stud is approximately 4 1/4 inches above the stringline when trailing a grid of 45° below horizontal.

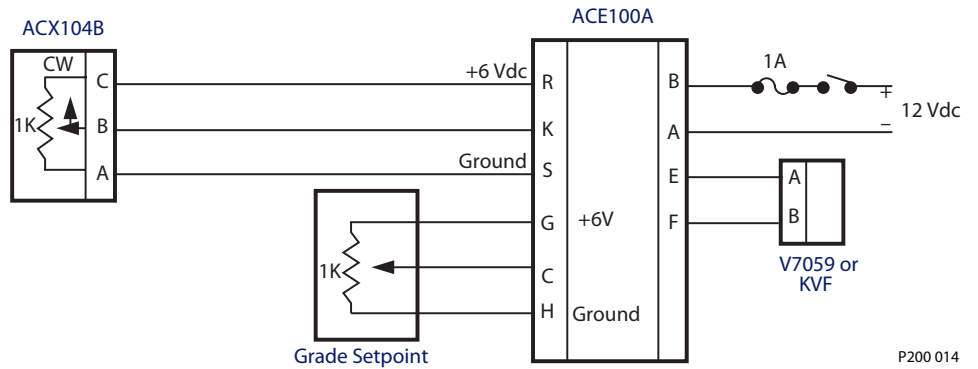
**Mounting**

The 1/2 inch bolt extending from the case is a rotatable mounting, allowing for proper leveling. It is important that the ACX104B be level in the plane of rotation around this pivot. In grade application, an improper mounting will cause the follower attachment to move up or down on a level surface as the machine moves closer or farther from the stringline. Use a Right Angle Follower (KG04001), skate assembly (KG06001), ski assembly (KG02001) or steering follower (KG07001) for contact to the reference surface.

#### Wiring

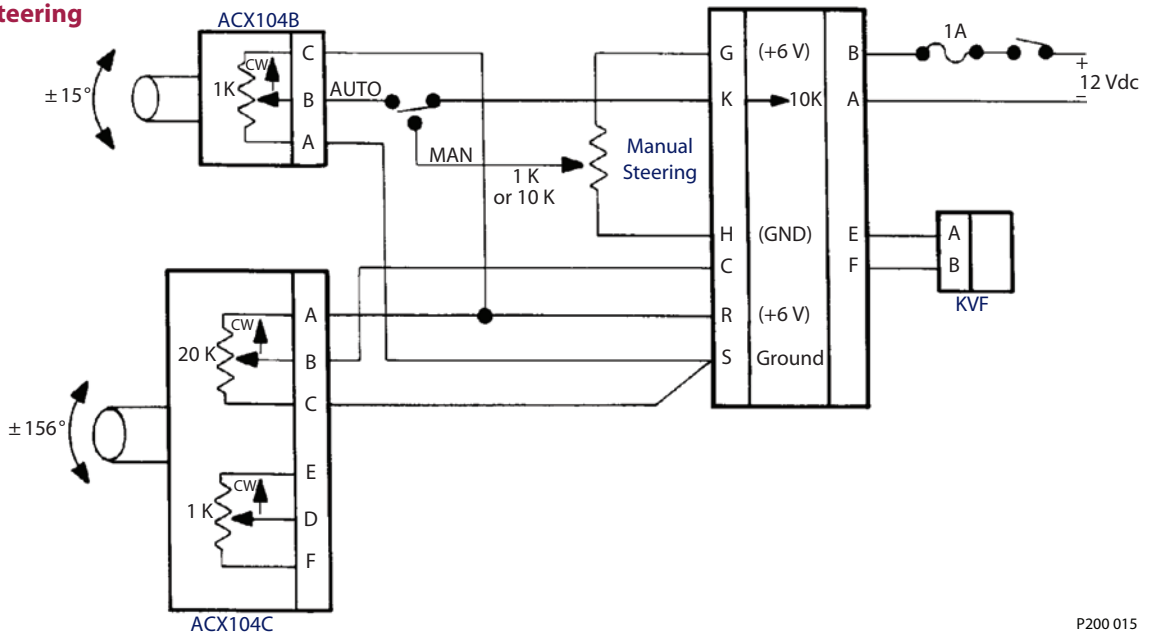
Direct connections are made through a Bendix MS3102A- 14S-6P (K04183) box receptacle on the case exterior. Connect a 134019ACAA (KW01009) cable to this receptacle. Terminate the other end of the cable with an MS3102A-14S-6P (K04183) bulkhead connector. Wire the bulkhead connector directly to the controller. Reference below schematics: *Connection Diagrams — Representative Proportional Rotary Position Control* and *Representative Proportional Steering Control*, or the simple schematic: *Connection Diagram — Representative Other Wiring Considerations*.

#### Connection Diagram— Proportional Rotary Position Control



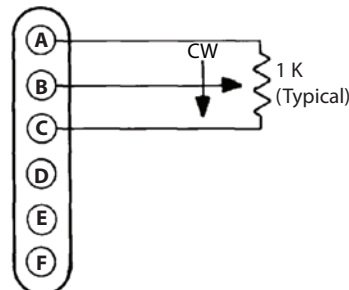
P200 014

#### Connection Diagram— Proportional Steering Control



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#### Connection Diagram— Other Wiring Considerations



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